

Elliptic boundary value problems with critical and supercritical nonlinearities. Part 1.

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Flagstaff, June 2012

Introduction

The problem

- We consider the problem

$$(\mathcal{P}_p) \quad \begin{cases} -\Delta u = |u|^{p-2} u & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

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Introduction

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Introduction

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Introduction

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Introduction

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- Throughout this talk $p = 2^*$.

Introduction

Why study the critical problem?

Some reasons for studying (\mathcal{P}_{2^*}) :

- 1 It is a simplified model for fundamental problems in Differential Geometry, e.g.

Introduction

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Introduction

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Introduction

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Introduction

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Introduction

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- 3 It has a rich geometric structure.

Introduction

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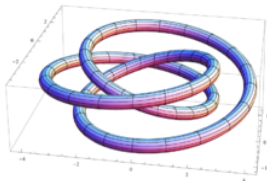
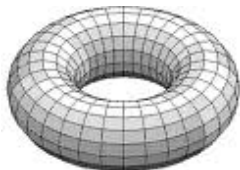
Some reasons for studying (\mathcal{P}_{2^*}) :

- 1 It is a simplified model for fundamental problems in Differential Geometry, e.g.
 - the Yamabe problem,
 - the prescribed curvature problem.
- 2 It gives rise to an interesting and challenging variational problem:
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- 3 It has a rich geometric structure.
- 4 It has been an amazing source of open problems and new ideas.

Introduction

The Yamabe problem

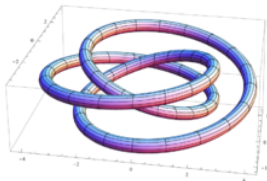
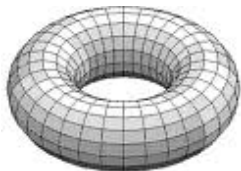
- Let M be a compact Riemannian manifold.



Introduction

The Yamabe problem

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- Two metrics g and \bar{g} on M are *conformally equivalent* if there exists a smooth function $\rho > 0$ such that $\bar{g} = \rho g$.

Introduction

The Yamabe problem

- In dimension 2 one has the classical result:

Introduction

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Theorem (Klein-Poincaré uniformization theorem)

Every surface admits a metric of constant curvature.

Introduction

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If (M, g) , $\dim M \geq 3$, does there exist a metric \bar{g} conformally equivalent to g such that (M, \bar{g}) has constant scalar curvature?

Introduction

The Yamabe problem

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Introduction

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Introduction

The Yamabe problem

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- Trudinger (1968) found a fundamental mistake in Yamabe's proof.

Introduction

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Theorem (Yamabe, Trudinger, Aubin 1976, Schoen 1984)

The answer to Yamabe's problem is YES.

Introduction

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Theorem (Yamabe, Trudinger, Aubin 1976, Schoen 1984)

The answer to Yamabe's problem is YES.

- If we write $\rho := u^{2^*-2}$ and $\bar{g} := \rho g$, then the scalar curvatures R_g of (M, g) and $R_{\bar{g}}$ of (M, \bar{g}) satisfy

$$-c_N \Delta_g u + R_g u = R_{\bar{g}} u^{2^*-1} \quad \text{on } M.$$

The variational problem

The functional

Mónica Clapp

Introduction

Yamabe's
problem

The
variational
problem

The classical
results

The geometric
structure

Multiple
solutions

Punctured
domains

Symmetries

Thin holes

The end

- The solutions to problem

$$(\wp_p) \quad \begin{cases} -\Delta u = |u|^{p-2} u & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad p \in (2, 2^*],$$

$\Omega \subset \mathbb{R}^N$ bounded smooth domain, $N \geq 3$, $2^* := \frac{2N}{N-2}$,

The variational problem

The functional

Mónica Clapp

Introduction

Yamabe's
problemThe
variational
problemThe classical
resultsThe geometric
structureMultiple
solutionsPunctured
domains

Symmetries

Thin holes

The end

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$\Omega \subset \mathbb{R}^N$ bounded smooth domain, $N \geq 3$, $2^* := \frac{2N}{N-2}$,

- are the critical points of

$$J_p(u) = \frac{1}{2} \|u\|_{H_0^1}^2 - \frac{1}{p} \|u\|_{L^p}^p, \quad u \in H_0^1(\Omega),$$

The variational problem

The functional

Mónica Clapp

Introduction

Yamabe's
problemThe
variational
problemThe classical
resultsThe geometric
structureMultiple
solutionsPunctured
domains

Symmetries

Thin holes

The end

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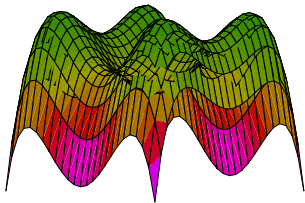
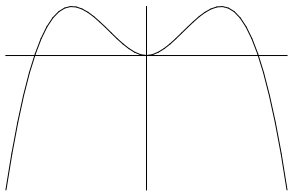
$$J_p(u) = \frac{1}{2} \|u\|_{H_0^1}^2 - \frac{1}{p} \|u\|_{L^p}^p, \quad u \in H_0^1(\Omega),$$

- where $\|u\|_{H_0^1}^2 := \int_{\Omega} |\nabla u|^2$.

The variational problem

The graph of the functional

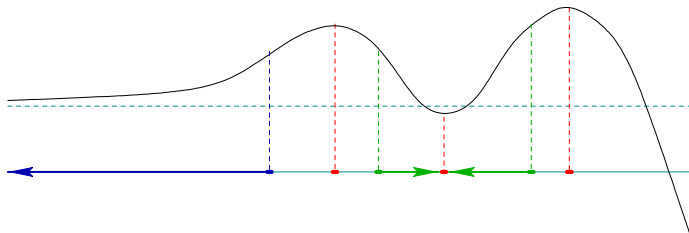
$$J_p(u) = \frac{1}{2} \|u\|_{H_0^1}^2 - \frac{1}{p} \|u\|_{L^p}^p, \quad p \in (2, 2^*].$$



The variational problem

Variational methods

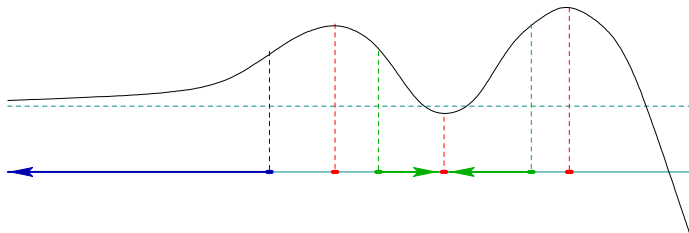
- Variational methods: Follow the negative gradient flow to obtain critical points.



The variational problem

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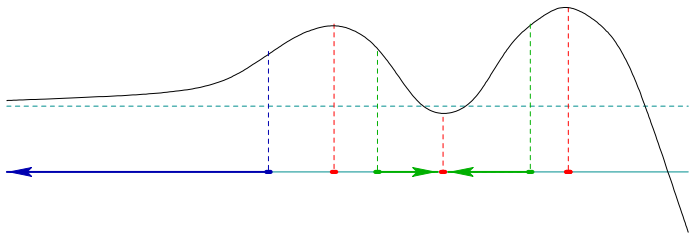


- The problem is: The flow lines do not necessarily take us to a critical point!

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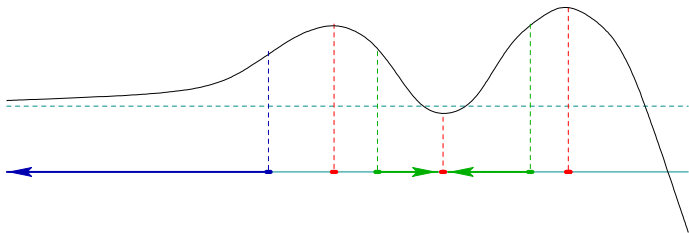


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The variational problem

Variational methods

- Variational methods: Follow the negative gradient flow to obtain critical points.



- The problem is: The flow lines do not necessarily take us to a critical point!
 - They do if $p < 2^*$.
 - But not necessarily when $p = 2^*$.

The variational problem

supercritical vs subcritical

Mónica Clapp

Introduction

Yamabe's
problem

The
variational
problem

The classical
results

The geometric
structure

Multiple
solutions

Punctured
domains

Symmetries

Thin holes

The end

In fact,

- if $p \in (2, 2^*)$ variational methods give infinitely many solutions to problem

$$(\mathcal{P}_p) \quad \begin{cases} -\Delta u = |u|^{p-2} u & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

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The variational problem

supercritical vs subcritical

Mónica Clapp

Introduction

Yamabe's
problem

The
variational
problem

The classical
results

The geometric
structure

Multiple
solutions

Punctured
domains

Symmetries

Thin holes

The end

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The variational problem

supercritical vs subcritical

Mónica Clapp

Introduction

Yamabe's
problem

The
variational
problem

The classical
results

The geometric
structure

Multiple
solutions

Punctured
domains

Symmetries

Thin holes

The end

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whereas,

- if $p \geq 2^*$ there are domains Ω for which the problem has no solution,
 - e.g. $\Omega = \text{ball}$.
 - the existence of solutions depends on Ω .

The classical results

Nonexistence

Theorem (Pohozaev 1965)

Problem

$$(\mathcal{P}_p) \quad \begin{cases} -\Delta u = |u|^{p-2} u & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

with $p \geq 2^$ does not have a nontrivial solution if Ω is strictly starshaped.*

The classical results

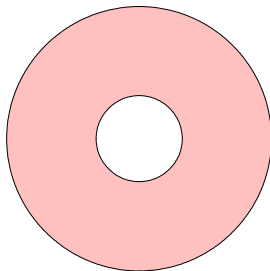
Existence

Theorem (Kazdan-Warner 1975)

If Ω is an annulus, i.e.

$$\Omega = \{x \in \mathbb{R}^N : 0 < a < |x| < b\},$$

then (ϕ_p) has infinitely many radial solutions for every $p > 2$.



The classical results

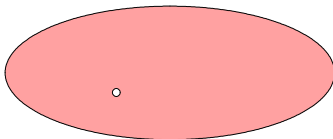
Existence in punctured domains

Theorem (Coron 1984)

Let Ω be a bounded smooth domain, $\xi \in \Omega$ and $\varepsilon > 0$. Then

$$(\mathcal{P}^{2^*,\varepsilon}) \quad \begin{cases} -\Delta u = |u|^{2^*-2} u & \text{in } \Omega_\varepsilon := \Omega \setminus B_\varepsilon(\xi), \\ u = 0 & \text{on } \partial\Omega_\varepsilon, \end{cases}$$

has a positive solution for ε small enough.

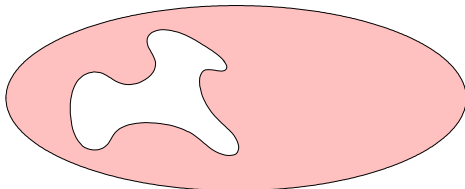


The classical results

Existence

Theorem (Bahri-Coron 1988)

If $\tilde{H}_*(\Omega; \mathbb{Z}/2) \neq 0$, then (φ_{2^*}) has a positive solution.



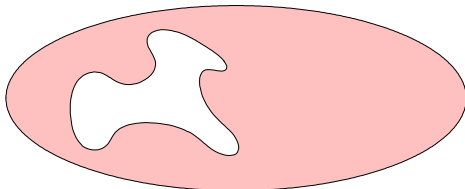
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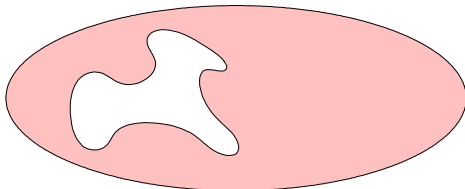
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The classical results

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- *The proof relies on the fact that one knows all positive solutions to the problem in \mathbb{R}^N .*
- *It uses delicate estimates and*
- *sophisticated tools from algebraic topology.*

The classical results

Existence in contractible domains

- Is it true that there is no solution if Ω is contractible?

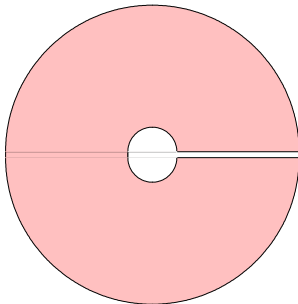
The classical results

Existence in contractible domains

- Is it true that there is no solution if Ω is contractible?

Examples (Dancer 1988, Ding 1989, Passaseo 1989)

There are nontrivial solutions in some contractible domains, e.g.



Annulus with a very thin tunnel

The geometric structure

Möbius invariance

- If u is a solution to

$$\begin{cases} -\Delta u = |u|^{p-2} u & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

The geometric structure

Möbius invariance

Mónica Clapp

Introduction

Yamabe's
problem

The
variational
problem

The classical
results

The geometric
structure

Multiple
solutions

Punctured
domains

Symmetries

Thin holes

The end

- If u is a solution to

$$\begin{cases} -\Delta u = |u|^{p-2} u & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

- then, for any Möbius transformation

$$\phi : \mathbb{R}^N \cup \{\infty\} \rightarrow \mathbb{R}^N \cup \{\infty\},$$

The geometric structure

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Mónica Clapp

Introduction

Yamabe's
problemThe
variational
problemThe classical
resultsThe geometric
structureMultiple
solutionsPunctured
domains

Symmetries

Thin holes

The end

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$$\phi : \mathbb{R}^N \cup \{\infty\} \rightarrow \mathbb{R}^N \cup \{\infty\},$$

- the function

$$u_\phi := |\det D\phi|^{\frac{1}{2^*}} (u \circ \phi)$$

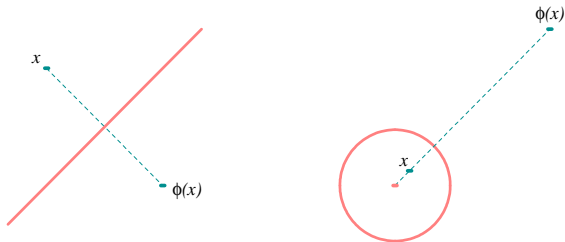
is a solution to

$$\begin{cases} -\Delta u_\phi = |u_\phi|^{2^*-2} u_\phi & \text{in } \phi^{-1}(\Omega), \\ u_\phi = 0 & \text{on } \partial(\phi^{-1}(\Omega)). \end{cases}$$

The geometric structure

Möbius transformations

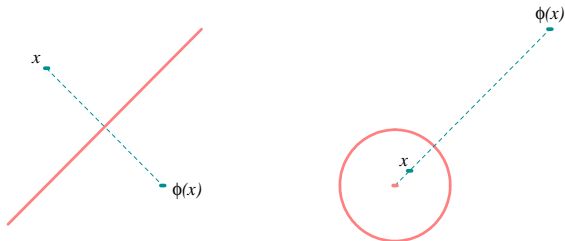
- A **Möbius transformation** is a finite composition of reflections on planes and inversions on spheres.



The geometric structure

Möbius transformations

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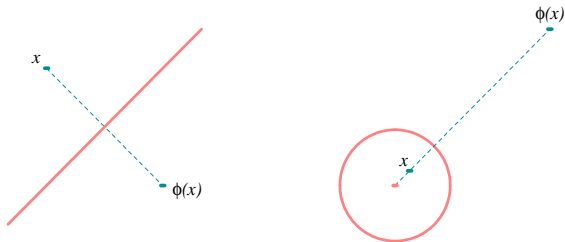


- Examples:

The geometric structure

Möbius transformations

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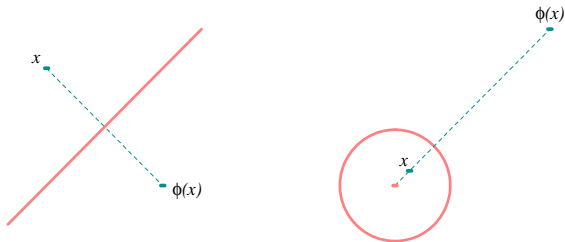


- Examples:
 - euclidean isometries, i.e. translations and linear isometries,

The geometric structure

Möbius transformations

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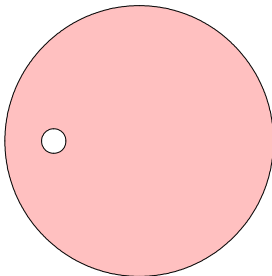
- Examples:
 - euclidean isometries, i.e. translations and linear isometries,
 - dilations: $x \mapsto \lambda x$, $\lambda > 0$.

The geometric structure

Multiplicity in domains with spherical boundaries

Example (C.-Pacella 2008)

If $\partial\Omega =$ union of two disjoint spheres, then problem (\wp_{2^*}) has infinitely many solutions.



The geometric structure

Multiplicity in domains with spherical boundaries

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The geometric structure

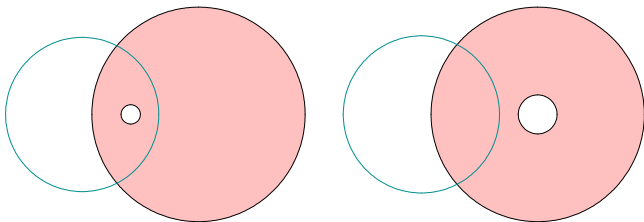
Multiplicity in domains with spherical boundaries

Examples (C.-Pacella 2008)

If $\partial\Omega =$ union of two disjoint spheres, then problem (\wp_{2^*}) has infinitely many solutions.

Proof.

There exists an inversion which maps Ω onto an annulus:



The geometric structure

Positive entire solutions

Introduction

Yamabe's
problem

The
variational
problem

The classical
results

The geometric
structure

Multiple
solutions

Punctured
domains

Symmetries

Thin holes

The end

- Consider the problem in \mathbb{R}^N

$$(\mathcal{P}_{\mathbb{R}^N}) \quad \begin{cases} -\Delta u = |u|^{2^*-2} u & \text{in } \mathbb{R}^N, \\ u(x) \rightarrow 0 & \text{as } |x| \rightarrow \infty. \end{cases}$$

The geometric structure

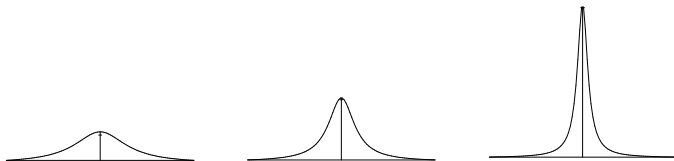
Standard bubbles

Theorem (Aubin, Talenti 1976, Gidas-Ni-Nirenberg 1979, Lions 1985)

The standard bubble

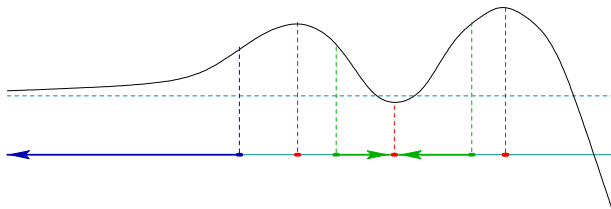
$$U(x) = a_N \left(\frac{1}{1 + |x|^2} \right)^{\frac{N-2}{2}}$$

is the only positive solution to $(\mathcal{P}_{\mathbb{R}^N})$, up to translations and dilations.



The geometric structure causes blow-up in bounded domains

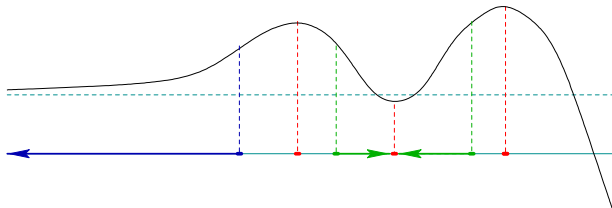
- As for



The geometric structure

causes blow-up in bounded domains

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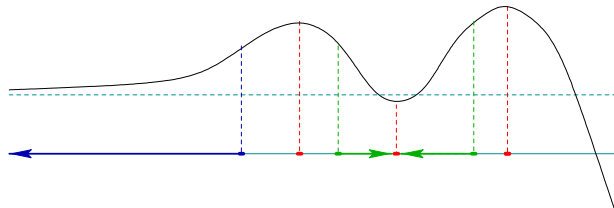


- if Ω is a bounded domain, there are trajectories $t \mapsto u_t$ in $H_0^1(\Omega)$, such that

$$J(u_t) \rightarrow c, \quad \nabla J(u_t) \rightarrow 0, \quad \text{as } t \rightarrow \infty,$$

The geometric structure causes blow-up in bounded domains

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- if Ω is a bounded domain, there are trajectories $t \mapsto u_t$ in $H_0^1(\Omega)$, such that

$$J(u_t) \rightarrow c, \quad \nabla J(u_t) \rightarrow 0, \quad \text{as } t \rightarrow \infty,$$

- but (u_t) does not converge to a critical point as $t \rightarrow \infty$!

The geometry of the problem

causes blow-up in bounded domains

- They look like this:

The geometry of the problem

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Introduction

Yamabe's
problem

The
variational
problem

The classical
results

**The geometric
structure**

Multiple
solutions

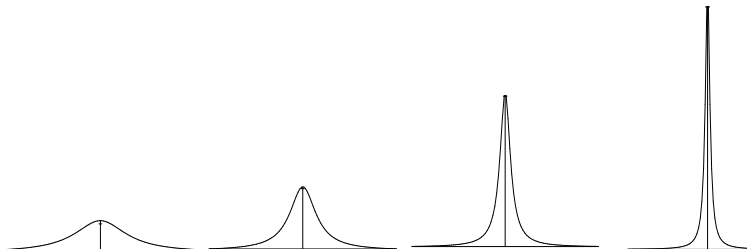
Punctured
domains

Symmetries

Thin holes

The end

- They look like this:



The geometry of the problem

causes blow-up in bounded domains

Introduction

Yamabe's
problem

The
variational
problem

The classical
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The geometric
structure

Multiple
solutions

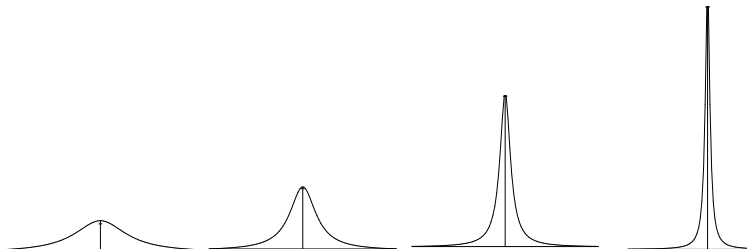
Punctured
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- **Struwe (1984)** showed that the lack of compactness is solely due to this phenomenon.

Multiple solutions

Our program

- We now go back to the problem

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in a bounded smooth domain $\Omega \subset \mathbb{R}^N$, $N \geq 3$,
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Answers & methods

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Multiple solutions

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 - the symmetries help us deal with the lack of compactness.

Multiple solutions

In punctured domains

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Multiple solutions

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have more than one solution for $\varepsilon > 0$ small enough?

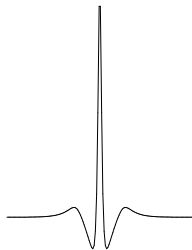
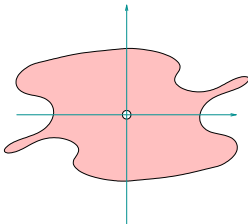
Multiple solutions

In punctured domains

Theorem (Ge-Musso-Pistoia 2010)

$$\# \text{ of solutions to } (\varphi_{2^*,\varepsilon}) \xrightarrow{\varepsilon \rightarrow 0} \infty.$$

- The solutions look like superpositions of standard bubbles with alternating signs (*bubble towers*):



Symmetries

The energy functional

- Recall that the solutions to

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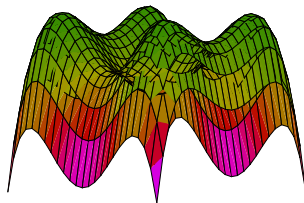
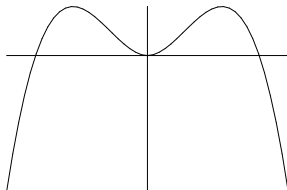
- are the critical points of the functional

$$J(u) = \frac{1}{2} \|u\|_{H_0^1}^2 - \frac{1}{2^*} \|u\|_{L^{2^*}}^{2^*}, \quad u \in H_0^1(\Omega).$$

Symmetries

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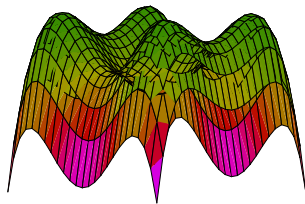
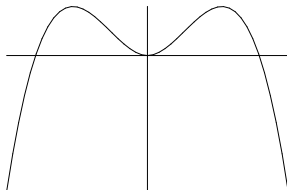
- J has the mountain pass geometry:



Symmetries

The energy functional

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- but the first mountain pass is never attained!!!

Symmetries

and variational methods

- Let $G \subset O(N)$ be a group of linear isometries of \mathbb{R}^N .

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- They are the critical points of the restriction of

$$J(u) = \frac{1}{2} \|u\|_{H_0^1}^2 - \frac{1}{2^*} \|u\|_{L^{2^*}}^{2^*}$$

to the subspace

$$H_0^1(\Omega)^G := \{u \in H_0^1(\Omega) : u \text{ is } G\text{-invariant}\}.$$

Symmetries

produce compactness

Theorem (compactness)

If

$$c < \min_{x \in \bar{\Omega}} (\#Gx) c_{\infty}, \quad c_{\infty} := \frac{1}{N} S^{N/2},$$

then J satisfies the Palais-Smale $(PS)_c^G$, i.e.

- every sequence s.t.*

$$u_n \in H_0^1(\Omega)^G, \quad J(u_n) \rightarrow c, \quad \nabla J(u_n) \rightarrow 0,$$

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Corollary

If $\#Gx = \infty$ for every $x \in \overline{\Omega}$ then problem (\wp_{2^}) has infinitely many solutions.*

Symmetries

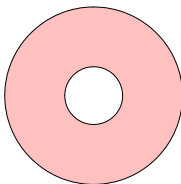
produce compactness

Example (Kazdan-Warner)

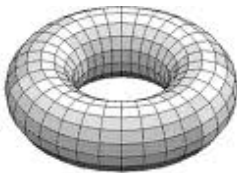
If $G = O(N)$ and $\Omega = \text{annulus}$, then problem (\wp_{2^*}) has infinitely many radial solutions.

Example

If $G = SO(2)$ and $\Omega = \text{torus}$, then (\wp_{2^*}) has infinitely many solutions which are invariant under rotations.



annulus



torus

Symmetries

The orbits must be infinite

Example (Pohozaev)

If $G = O(N)$ and $\Omega = \text{ball}$, problem $(\mathcal{P}2^*)$ does not have a nontrivial solution!!!



Domains with a thin hole

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Domains with a thin hole

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Introduction

Yamabe's
problem

The
variational
problem

The classical
results

The geometric
structure

Multiple
solutions

Punctured
domains

Symmetries

Thin holes

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Domains with a thin hole

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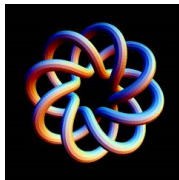
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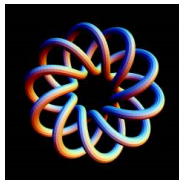
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G_5 -inv.



G_8 -inv.



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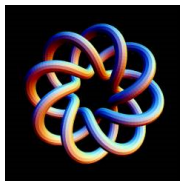
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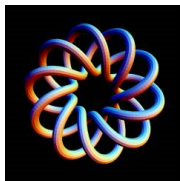
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- Then $\Omega_\varepsilon := \{x \in \Omega : \text{dist}(x, M) > \varepsilon\}$ is G_n -invariant, but $\#G_n x = n < \infty$.

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A trick to produce sign changing solutions

- Let $\tau : G \rightarrow \mathbb{Z}/2 := \{1, -1\}$ be a group homomorphism.

Domains with a thin hole

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- Therefore, if τ is surjective, u changes sign.

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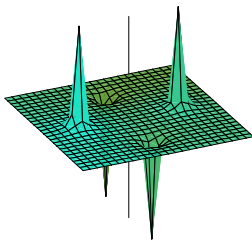
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- A function satisfying $u(gx) = \tau(g)u(x)$ for G_4 is:



Domains with a thin hole

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Domains with a thin hole

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Introduction

Yamabe's
problem

The
variational
problem

The classical
results

The geometric
structure

Multiple
solutions

Punctured
domains

Symmetries

Thin holes

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Theorem (C.-Grossi-Pistoia ~2010)

For each $\varepsilon > 0$ sufficiently small problem $(\mathcal{P}_{2^,\varepsilon})$ has at least one nontrivial solution u which satisfies*

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The
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The geometric
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Multiple
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Punctured
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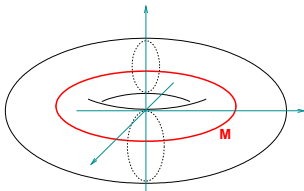
Domains with a thin hole

Multiplicity in highly symmetric domains

Example

$\Omega \subset \mathbb{R}^3$ a solid of revolution about the z -axis, $M := \mathbb{S}^1 \times \{0\}$ such that

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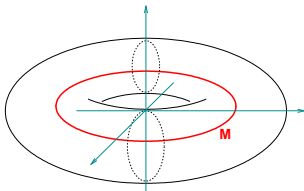
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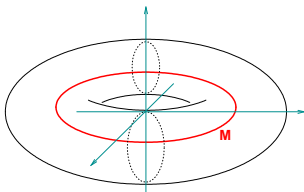
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- Ω_ε is invariant under rotations about the z -axis, hence
- (φ_ε) has infinitely many rotationally invariant solutions.

Domains with a thin hole

Multiplicity in highly symmetric domains

Corollary

Let $m \in \mathbb{N}$, Ω and M as above Then, for ε small enough, (φ_ε) has m pairs of solutions $\pm u_1, \dots, \pm u_m$ such that

$$u_n(\varrho_{2^n}^k x) = (-1)^k u_n(x), \quad k = 0, 1, \dots, 2^n - 1.$$

Domains with a thin hole

Multiplicity in highly symmetric domains

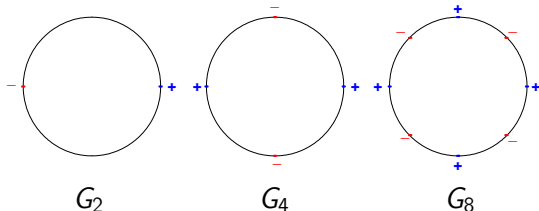
Corollary

Let $m \in \mathbb{N}$, Ω and M as above. Then, for ε small enough, (φ_ε) has m pairs of solutions $\pm u_1, \dots, \pm u_m$ such that

$$u_n(\varrho_{2^n}^k x) = (-1)^k u_n(x), \quad k = 0, 1, \dots, 2^n - 1.$$

Proof.

We apply the previous theorem to the group G_{2^n} :



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- *work in progress by Juan Carlos Fernández shows there are at least two solutions.*

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The classical
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- *Is it true that, as for punctured domains, the number of solutions increases arbitrarily as $\varepsilon \rightarrow 0$?*
- *Are there bubble towers?*
- *Are there multibump solutions?*
- *Are there solutions with layers concentrating along M as $\varepsilon \rightarrow 0$?*

Thanks

Thank you very much for your attention !