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Fredholm Alternative for the p -Laplacian: Variational Approach (2nd plenary lecture)

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Recall that $\lambda_1 > 0$ is the first eigenvalue of

$$\begin{cases} -\Delta_p u = \lambda |u|^{p-2} u & \text{in } \Omega, \\ u|_{\partial\Omega} = 0 \end{cases}$$

$\varphi_1 > 0$ corresponding eigenfunction

We focus on the geometry of the energy

$$E_\lambda(u) := \frac{1}{p} \int_{\Omega} |\nabla u|^p - \frac{\lambda}{p} \int_{\Omega} |u|^p - \int_{\Omega} f u, \quad u \in W_0^{1,p}$$

where $\lambda = \lambda_1$ or λ close to λ_1 , $\int_{\Omega} f \varphi_1 = 0$ or "small"

$$\langle E'_\lambda(u), v \rangle = \int_\Omega |\nabla u|^{p-2} \nabla u \cdot \nabla v - \lambda \int_\Omega |u|^{p-2} u v - \int_\Omega f v$$

critical point u_0 : $\langle E'_\lambda(u_0), v \rangle = 0 \quad \forall v$

u_0 is a weak sol'n of

$$-\Delta_p u = \lambda |u|^{p-2} u + f \quad \text{in } \Omega, \quad u|_{\partial\Omega} = 0.$$

We consider first $\lambda = \lambda_1$ & $\int_\Omega f \varphi_1 = 0$.

For $p=2$ the geometry of

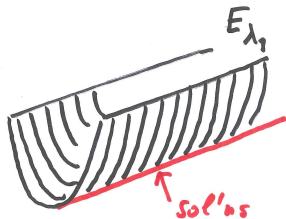
$$E_{\lambda_1}(u) = \frac{1}{2} \int_{\Omega} |\nabla u|^2 - \frac{\lambda_1}{2} \int_{\Omega} |u|^2 - \int_{\Omega} f u, u \in W_0^{1,2}$$

corresponds to "infinitely long" through with the bottom formed by one-dim. affine set of solutions to

$$\begin{cases} -\Delta u = \lambda_1 u + f & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

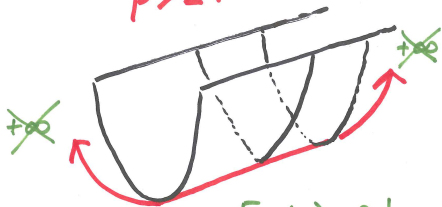
provided

$$\int_{\Omega} f \varphi_1 = 0.$$



For $p \neq 2$ the geometry of E_{λ_1} corresponds to a deformation of the trough which is different for $1 < p < 2$ and $p > 2$.

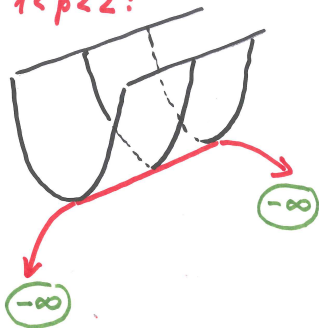
$p > 2$:



$$E_{\lambda_1}(\varphi_1) = 0!$$

$$\int_{\Omega} f \varphi_1 = 0$$

$1 < p < 2$:



$p \neq 2$: critical points of E_{λ_1} are
a priori bounded

$p > 2$: E_{λ_1} is bounded from below
it has a global minimizer
it is not coercive
($E_{\lambda_1}(t\varphi_1) = 0 \quad \forall t \in \mathbb{R}$)

$1 < p < 2$: E_{λ_1} is unbounded from below
(and from above)
it has a saddle point
P.-S. condition not available

For $p > 2$ the following generalization of the Poincaré inequality was proved in

Fleckinger, Takač (Adv. Diff. Eq. 2002) :

$$u = \bar{u} \varphi_1 + \tilde{u}, \quad \bar{u} := \frac{\int_{\Omega} u \varphi_1}{\left(\int_{\Omega} \varphi_1^2\right)^{1/2}}, \quad \int_{\Omega} \tilde{u} \varphi_1 = 0$$

Poincaré $p = 2$:
$$\int_{\Omega} |\nabla u|^2 - \lambda_1 \int_{\Omega} |u|^2 \geq (\lambda_2 - \lambda_1) \int_{\Omega} |\tilde{u}|^2$$

$p \neq 2$: $\exists c > 0$:

$$\int_{\Omega} |\nabla u|^p - \lambda_1 \int_{\Omega} |u|^p \geq c \left(\underbrace{|\bar{u}|^{p-2} \int_{\Omega} |\nabla \varphi_1|^{p-2} |\nabla \tilde{u}|^2}_{\text{extra term for } p \neq 2} + \int_{\Omega} |\nabla \tilde{u}|^p \right)$$

Consequently :

$$\int_{\Omega} |\nabla u|^p - \lambda_1 \int_{\Omega} |u|^p \geq \tilde{c} \left(|\bar{u}|^{p-2} \int_{\Omega} |\tilde{u}|^2 + \int_{\Omega} |\tilde{u}|^p \right).$$

The boundedness of E_{λ_1} from below follows :

$$\begin{aligned} E_{\lambda_1}(u) &= \frac{1}{p} \int_{\Omega} |\nabla u|^p - \frac{\lambda_1}{p} \int_{\Omega} |u|^p - \int_{\Omega} f u \\ &\geq \frac{\tilde{c}}{p} \left(|\bar{u}|^{p-2} \int_{\Omega} |\tilde{u}|^2 + \int_{\Omega} |\tilde{u}|^p \right) - \int_{\Omega} f \tilde{u} \\ &\geq \left[\frac{\tilde{c}}{p} \left(\int_{\Omega} |\tilde{u}|^p \right)^{\frac{1}{p'}} - \left(\int_{\Omega} |f|^p \right)^{\frac{1}{p'}} \right] \left(\int_{\Omega} |\tilde{u}|^p \right)^{\frac{1}{p}} + \frac{\tilde{c}}{p} |\bar{u}|^{p-2} \int_{\Omega} |\tilde{u}|^2. \end{aligned}$$

In Dr. + Takač (Calc. Variations 2007):

$p > 2$: E_λ satisfies P.-S. condition
on level $c < 0$ (it is violated
on level $c = 0$)



minimization argument and
boundedness from below yields
the existence of global minimizer

For $1 < p < 2$ the geometry of a saddle point was proved in Drábek, Holubová (J. Math. Anal. Appl. 2001):

$$\tilde{W}_0^{1,p}(\Omega) := \left\{ u \in W_0^{1,p}(\Omega) : \int_{\Omega} u \varphi_1 = 0 \right\}$$

$$\exists c > 0 : \frac{1}{p} \int_{\Omega} |\nabla \tilde{u}|^p - \frac{\lambda_2}{p} \int_{\Omega} |\tilde{u}|^p \geq c \int_{\Omega} |\nabla \tilde{u}|^p$$

(proof by contradiction)

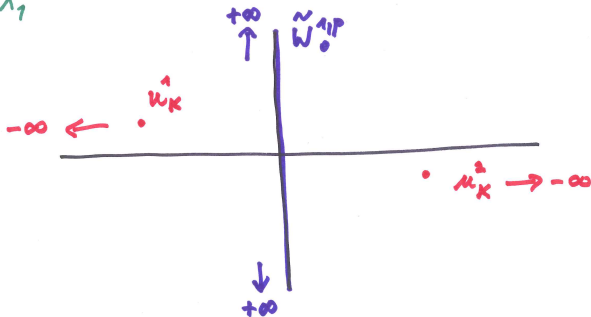
$$\begin{aligned} E_{\lambda_2}(u) &= \frac{1}{p} \int_{\Omega} |\nabla \tilde{u}|^p - \frac{\lambda_2}{p} \int_{\Omega} |\tilde{u}|^p - \int_{\Omega} f \tilde{u} \geq \\ &\geq c \int_{\Omega} |\nabla \tilde{u}|^p - \left(\int_{\Omega} |f|^p \right)^{\frac{1}{p}} \left(\int_{\Omega} |\tilde{u}|^p \right)^{\frac{1}{p}} \end{aligned}$$

bad below
coercive
on $\tilde{W}_0^{1,p}$

On the other hand, $\forall K > 0 \exists u_K^1, u_K^2$
 u_K^1 and u_K^2 are separated by $\tilde{W}_0^{1,p}$:

$$E_{\lambda_1}(u_K^i) < -K \quad , \quad i=1,2$$

(E_{λ_1} is unbounded from below on $W_0^{1,p}(\Omega)$)



For $v_t = \varphi_1 + t^{-1}w$ we expand:

$$J(v_t) = \frac{1}{p} \int_{\Omega} |\nabla \varphi_1 + \frac{1}{t} \nabla w|^p - \frac{\lambda_1}{p} \int_{\Omega} |\varphi_1 + \frac{1}{t} w|^p$$

$$= \underbrace{\frac{1}{p} \int_{\Omega} |\nabla \varphi_1|^p - \frac{\lambda_1}{p} \int_{\Omega} |\varphi_1|^p}_{=0} + \underbrace{\int_{\Omega} |\nabla \varphi_1|^{p-2} \nabla \varphi_1 \cdot \nabla \left(\frac{w}{t}\right) - \lambda_1 \int_{\Omega} |\varphi_1|^{p-2} \frac{w}{t}}_{=0}$$

$$+ \frac{1}{2} \left(\int_{\Omega} (p-2) |\nabla \varphi_1|^{p-2} \left(\frac{\nabla \varphi_1}{|\nabla \varphi_1|} \cdot \nabla \left(\frac{w}{t}\right) \right)^2 + \int_{\Omega} |\nabla \varphi_1|^{p-2} \left| \nabla \frac{w}{t} \right|^2 \right)$$

$$= \frac{1}{t^2} (\dots) - (p-1) \lambda_1 \int_{\Omega} |\varphi_1|^{p-2} \left(\frac{w}{t}\right)^2 + o\left(\frac{1}{t^2}\right), t \rightarrow \infty$$

Choose w such that $\int_{\Omega} f w > 0$ and

set

$$u_t^1 = t^{\frac{1}{p} + \frac{1}{2}} v_t = t^{\frac{1}{p} + \frac{1}{2}} \left(\varphi_1 + \frac{w}{t} \right).$$

Then

$$\begin{aligned} E_{\lambda_1}(u_t^1) &= J(t^{\frac{1}{p} + \frac{1}{2}} v_t) - \int_{\Omega} f u_t = t^{\frac{p}{2} + 1} J(v_t) - t^{\frac{1}{p} + \frac{1}{2}} \int_{\Omega} f \frac{w}{t} \\ &= \underbrace{\frac{1}{2} t^{\frac{p}{2} - 1} (\dots)}_{\rightarrow 0} + \underbrace{o\left(\frac{1}{t^2}\right)}_{\rightarrow 0} - \underbrace{t^{\frac{p}{2} - \frac{1}{2}} \int_{\Omega} f w}_{\rightarrow \infty} \\ &\rightarrow -\infty ! \end{aligned}$$

Similarly, if we choose $w: \int_{\Omega} fw < 0$

and consider

$$u_t^2 = -t^{\frac{1}{p} + \frac{1}{2}} v_t$$

we get $E_{\lambda_1}(u_t^2) \rightarrow -\infty$ as $t \rightarrow \infty$.

Moreover, u_t^1 and u_t^2 are separated by $\tilde{W}_0^{1,p}$ and for $t \gg 1$:

$$E_{\lambda_1}(u_t^{1,2}) < \inf_{\tilde{u} \in \tilde{W}_0^{1,p}} E(\tilde{u})$$

Observation. The saddle geometry of E_{λ_1} is preserved under small perturbations of f :

$$E_{\lambda_1}(u) = \frac{1}{p} \int_{\Omega} |\nabla u|^p - \frac{\lambda_1}{p} \int_{\Omega} |u|^p - \int_{\Omega} \tilde{f} u, \quad \int_{\Omega} \tilde{f} \varphi_1 = 0$$

has a saddle geometry

$$\Rightarrow \forall c: |c| \ll 1, c \neq 0, f = c \varphi_1 + \tilde{f}$$

$$E_{\lambda_1}^c(u) = \frac{1}{p} \int_{\Omega} |\nabla u|^p - \frac{\lambda_1}{p} \int_{\Omega} |u|^p - \int_{\Omega} f u$$

has still saddle geometry

Even if P.-S. condition is not available for E_{λ_1} ($\int_{\Omega} f \tilde{y} = 0!$), it holds true

for $E_{\lambda_1}^c$ with $c \neq 0$. (The proof relies on standard contradiction type argument.)

Combined with the geometry ($|c| \ll 1!$), we prove the existence of a saddle point of $E_{\lambda_1}^c$ ($c \neq 0$) using the "classical arguments".

The proof of the existence of a critical point of E_{λ_1} ($c=0$) relies on the following argument:

We choose $c_1 < 0 < c_2$, $|c_i| \ll 1$, and consider

$$f_i = c_i \varphi_i + \tilde{f}, \quad \int_{\Omega} \tilde{f} \varphi_i = 0, \quad i=1,2$$

$$E_{\lambda_i}^{c_i}(u) = \frac{1}{p} \int_{\Omega} |\nabla u|^p - \frac{\lambda_i}{p} \int_{\Omega} |u|^p - \int_{\Omega} f_i \cdot u$$

- satisfies P.-S. condition
- has geometry of saddle type

$\Rightarrow \exists u_1, u_2 \in W_0^{1,p}$ critical points of $E_{\lambda_i}^{c_i}, i=1,2.$

u_i are sol's of :

$$\begin{cases} -\Delta u = \lambda_1 |u|^{p-2} u + c_1 \varphi_1 + \tilde{f} & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

u_1 subsolution

u_2 supersolution

for

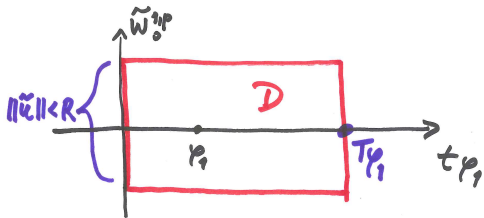
$$(*) \begin{cases} -\Delta_p u = \lambda_1 |u|^{p-2} u + \tilde{f} & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

Both well-ordered and non well-ordered case work in this case $\Rightarrow \exists$ solution of (*).

If $f = c\varphi_1 + \tilde{f}$, $c \neq 0$, $|c| \ll 1$,
 more careful analysis (P.D., EJDE 2002)
 of

$$E_{\lambda_1}^c(u) = \frac{1}{p} \int_{\Omega} |\nabla u|^p - \frac{\lambda_1}{p} \int_{\Omega} |u|^p - \int_{\Omega} f u$$

leads to : $\exists R > 0 \exists T > 0$ s.t.



$$\inf_D E_{\lambda_1}^c(u) < \inf_{\partial D} E_{\lambda_1}^c(u)$$

Since E_{λ_1} is bounded below on D ,

E_{λ_1} is w. l. s. c. $\Rightarrow \exists u_D \in D$:

$$E_{\lambda_1}^c(u_D) = \min_D E_{\lambda_1}^c(u).$$

$E_{\lambda_1}^c$ is unbounded from below on $W_0^{1,p}$

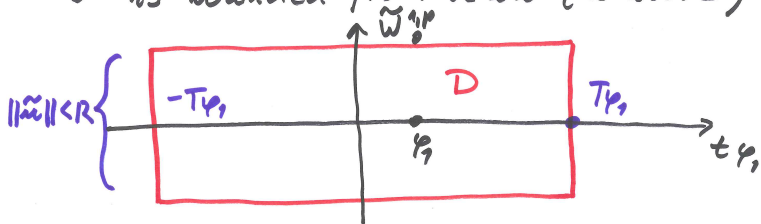
$\Rightarrow E_{\lambda_1}^c$ has a mountain-pass geometry ($c \neq 0$) + P.-S. cond.

$\Rightarrow \exists u_0 \neq u_D, (E_{\lambda_1}^c)'(u_0) = 0.$

For $p > 2$, $\int_{\Omega} \tilde{f} \varphi_1 = 0$ ($c = 0$)

$$E_{\lambda_1}(u) = \frac{1}{p} \int_{\Omega} |\nabla u|^p - \frac{\lambda_1}{p} \int_{\Omega} |u|^p - \int_{\Omega} \tilde{f} u$$

- is bounded from below (as above)



$$\inf_D E_{\lambda_1}(u) < \inf_{\partial D} E_{\lambda_1}(u)$$

$$c \neq 0, |c| \ll 1, f = c\varphi_1 + \tilde{f}$$

$$E_{\lambda_1}^c(u) = \frac{1}{p} \int_{\Omega} |\nabla u|^p - \frac{\lambda_1}{p} \int_{\Omega} |u|^p - \int_{\Omega} (c\varphi_1 + \tilde{f})u$$

$$u = t\varphi_1 + \tilde{u}$$

$$= E_{\lambda_1}(u) - \underbrace{ct \int_{\Omega} \varphi_1^2}_{\text{small perturbation on } D \text{ but unbounded on } W_0^{1,p}}$$

- $E_{\lambda_1}^c$ has a minimum over D
- $E_{\lambda_1}^c$ is unbounded from below on $W_0^{1,p}$
- $E_{\lambda_1}^c$ has a mountain-pass cr. point \Rightarrow 2nd sol'n

Fredholm alternative for the higher eigenvalues of the Dirichlet p -Laplacian:

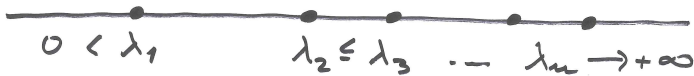
1. Manásevich, Takač (Proc. Lond. Math. Soc. 2002)
in 1 dimension, $\Omega = \text{interval}$
2. Benedikt, Ginz, Takač (Nonlinear Anal. 2010)
in higher dimension $\Omega \subseteq \mathbb{R}^N$

Asymptotic analysis is more difficult when the eigenfunction changes sign in Ω (even if $\Omega = \text{interval}$)!

OPEN PROBLEM # 1

$\sigma(\Delta_p)$... the set of all eigenvalues of
 $-\Delta_p u = \lambda |u|^{p-2} u$ in Ω , $u|_{\partial\Omega} = 0$.

$\sigma(\Delta_p)$ contains a sequence



$$\lambda_n = \inf \sup \dots \quad (= \sup \inf \dots)$$

For Ω bad domain, $\partial\Omega$ smooth

???. Find complete description of entire $\sigma(\Delta_p)$!!!

OPEN PROBLEM # 2

Let u_λ be an eigenfunction of

$$-\Delta_p u = \lambda |u|^{p-2} u \text{ in } \Omega, u|_{\partial\Omega} = 0$$

$u_\lambda \neq 0$! Ω bad domain, $\partial\Omega$ smooth

???. Does u_λ satisfy the Unique continuation property in the sense that the zero set of u_λ has empty interior ???

Thank you for your attention!

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